





Vetronics Technology Testbed

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30 May 2001

UNCLASSIFIED

Tank-automotive & Armaments COMmand

Report Documentation Page		
Report Date 30May2001	Report Type N/A	Dates Covered (from to)
Title and Subtitle Vetronics Technology Testbed		Contract Number
		Grant Number
		Program Element Number
Author(s) Novak, Brian		Project Number
		Task Number
		Work Unit Number
Performing Organization Name(s) and Address(es) U.S. Army Tank-Automotive RD&E Center (TARDEC) Vetronics Technology Area (AMSTA-TR-R, Mailstop 264) Warren, MI 48397-5000		C)
Sponsoring/Monitoring Agency Name(s) and Address(es)		Sponsor/Monitor's Acronym(s)
NDIA (National Defense Industrial Association) 211 Wilson Blvd, STE. 400 Arlington, VA 22201-3061		Sponsor/Monitor's Report Number(s)
Distribution/Availability Approved for public releas		
Supplementary Notes Proceedings from the 2001 Force, 29-31 May 2001 Sp	•	posium - Intelligent Systems for the Objective
Abstract		
Subject Terms		
Report Classification unclassified		Classification of this page unclassified
Classification of Abstract unclassified		Limitation of Abstract UU
Number of Pages 14		,

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Vetronics Technology Testbed (VTT) Program Overview



GOAL

Improve war fighting capability of ground combat vehicle systems

APPROACH

Develop advanced Vetronics technology for ground combat vehicles

Integrate into actual vehicle and demonstrate functionality

Conduct technology field tests and scout mission scenario experiments

Document results and use for future work





Vetronics Technology Testbed (VTT) Technologies



3D AUDIO Improve soldier situational awareness by spatializing

radio/intercom/WCA in three dimensions

SPEECH RECOGNITION Improve soldier efficiency by reducing time to input

commands

INDIRECT VISION DISPLAYS / Improve survivability by seating driver under armor

DRIVE BY WIRE Improve driving ability with displays rather than

vision blocks

ADVANCED ELECTRONICS Improve development/re-use using reference

ARCHITECTURE architecture, open standards, APIs

EMBEDDED SIMULATION Improve war fighting ability through simulated

training and mission rehearsal

ADVANCED CREW STATION Improve soldier effectiveness with multi-function

SOLDIER MACHINE INTERFACE displays



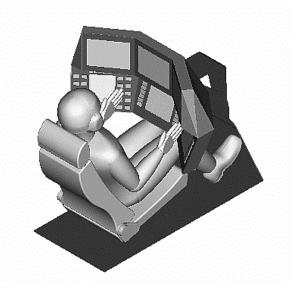
Vetronics Technology Testbed (VTT) Crew Station SMI



Crew Station SMI adapted from Crewman's Associate (CA) Advanced Technology Demonstrator (ATD)

SMI provides crew interface for:

- Command and Control (C2)
- Target Acquisition and Engagement
- Mobility
- System Control and Status
- Digital Map and Routing Planning
- Survivability
- Battlefield Visualization
- Embedded Training and Mission Rehearsal



Key Features

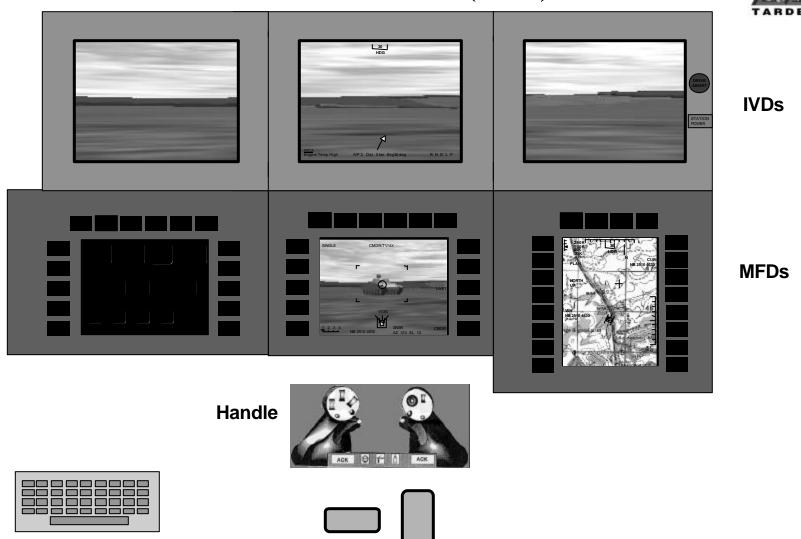
- Multi-Function Displays (MFDs) provides efficient use of hardware
- MFD Touch Screens for easy menu operation
- Bump Cursor allows hands-off menu operation
- Graphics overlay on driving video allows heads up driving
- Adaptable Graphics Interface Library (AGIL) Toolkit for commonality



Vetronics Technology Testbed (VTT) Crew Station SMI (cont)



Headset



Foot Pedals

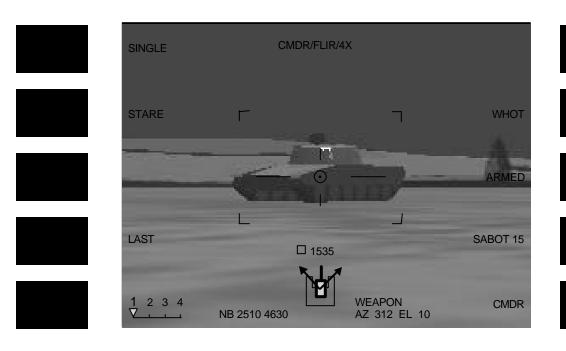
Keyboard



Vetronics Technology Testbed (VTT) Target Acquisition Function



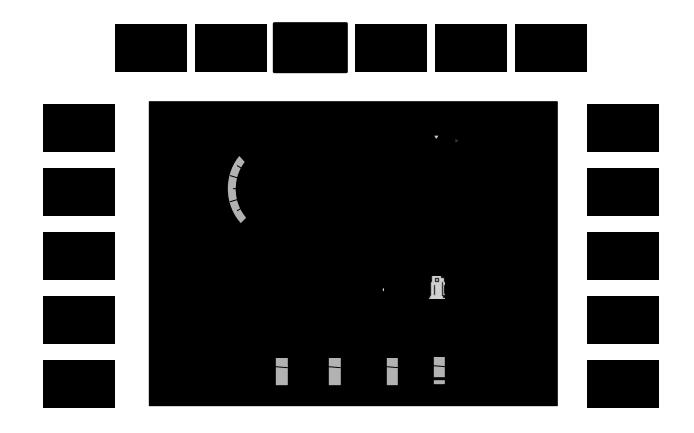






Vetronics Technology Testbed (VTT) Mobility Function

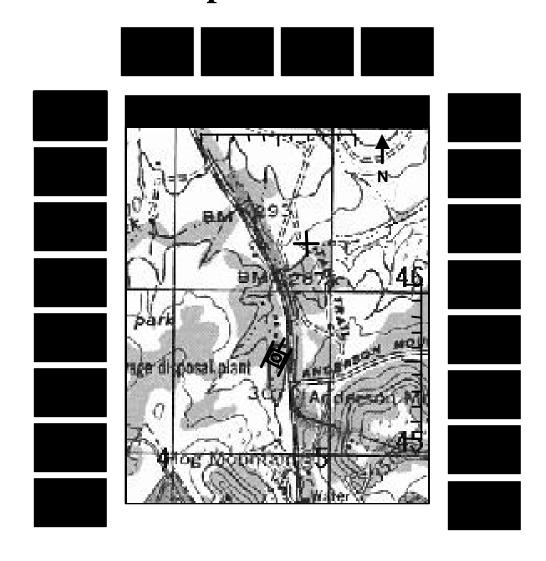






Vetronics Technology Testbed (VTT) Map Function

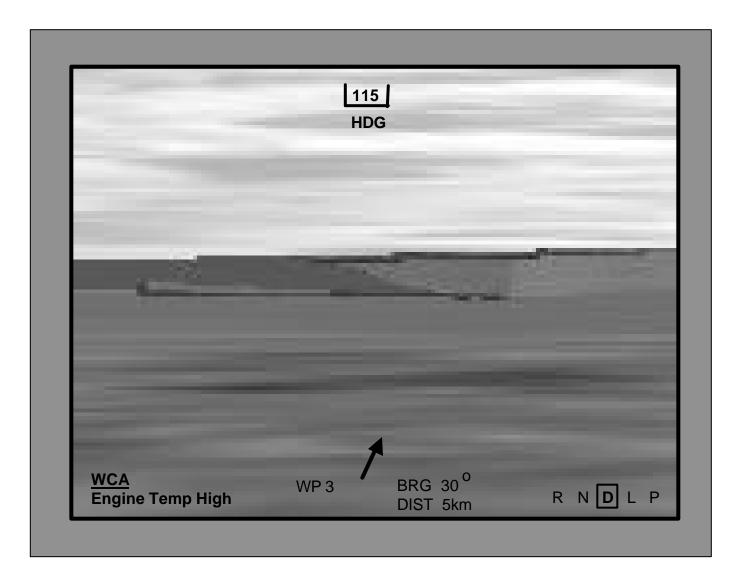






Vetronics Technology Testbed (VTT) Center Driving IVD with Overlay







Vetronics Technology Testbed (VTT) Integration





System Integration Lab (SIL)

Laboratory version of entire VTT system using commercial/industrial/mil hardware

Provides hardware integration and software development platform

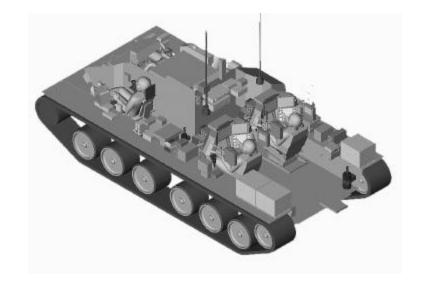
Able to checkout ruggedized hardware before integrating into vehicle

VTT Vehicle

Ruggedized version of VTT system using commercial/industrial/mil hardware

Bradley M2A0 platform (less turret)

Manned by a crew of three (one soldier at each station plus safety driver)





Vetronics Technology Testbed (VTT) Tests and Experiments



Indirect Vision and Drive By Wire Technology Tests June 4-15 2001

Determine the effects of indirect vision and drive by wire technology while performing various driving tasks:

Motor Pool Ops
Tactical Assembly
Road March
Vehicle Following
Tactical Night Driving

Measure visual acuity, time to completion, distance from obstacles, etc.

Bradley Fighting Vehicle (BFV) will be used as a baseline

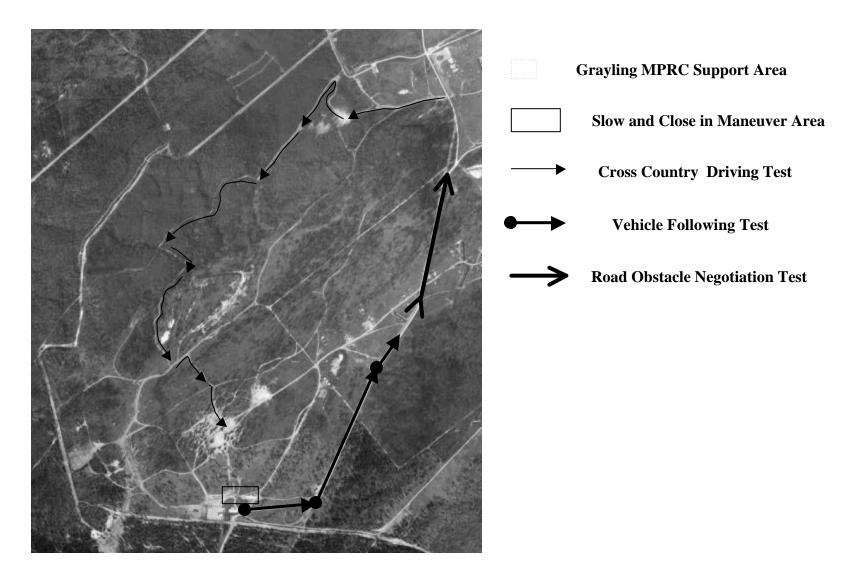
Designed and conducted by US Army Human Research and Engineering Directorate (HRED), Aberdeen Proving Ground, Maryland

Test site is Camp Grayling Military Reservation, Michigan



Vetronics Technology Testbed (VTT) Tests and Experiments (cont)







Vetronics Technology Testbed (VTT) Tests and Experiments (cont)



Speech Recognition and 3D Audio Technology Tests Sept-Oct 2001

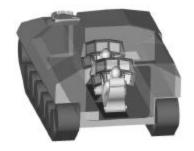
Determine the effects of speech recognition and 3D audio technology while performing multiple crew tasks

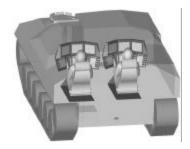
Being designed by US Army Human Research and Engineering Directorate (HRED), Aberdeen Proving Ground, Maryland

Scout Mission Scenarios Sept-Oct 2001

Two man crew to conduct military actions while stationary and on the move

Supported by the Mounted Maneuver Battle Lab (MMBL), Fort Knox, Kentucky





Measure human work load while crew conducts various day/night operations Raw data consists of video/audio and software data recording

Test site is Camp Grayling Military Reservation, Michigan



Vetronics Technology Testbed (VTT) Lessons Learned and Future Work



Lessons Learned

System Integration Lab (SIL) very useful during test and debug (test ruggedized hardware, vehicle cable harnesses, system software, etc.)

SIL uses MIL circular connectors. Need various test harnesses with commercial-mil connectors to test subsystems

Subsystem delivery schedule influenced by a hierarchy of sub-contractors/vendors

Vehicle power distribution system is non-trivial

Future Work

Continue to develop next generation crew station technology

Investigate helmet mounted displays (HMDs), collision warning systems, ...

Support CAT and RF ATDs with end goal to transfer technology to FCS